

A NUMERICAL MODELING OF A VARIABLE CONDUCTANCE THERMOSYPHON BY USE OF A BINARY MIXTURE

H. Shokohmand

*Department of Mechanical Engineering, Tehran University
Tehran, Iran, hshokoh@me.ut.ac.ir*

A. Hassani

*Branch of Science and Research, Islamic Azad University
Tehran, Iran, ab.hassani@parsonline.net*

(Received: November 19, 2001 – Accepted in Revised Form: October 10, 2002)

Abstract In this paper the steady state performance of a variable conductance heat pipe, which its working fluid consists of two components (R11+ R113) is modeled. The role of the liquid film momentum and axial normal stresses are considered by use of the mean property of mixture and the governing equations are solved by conventional numerical methods. The results of the present model have been compared with other numerical models and experimental works done by other investigators. The model presented could be used for optimization studies and design of variable conductance thermosyphons.

Key Words Thermosyphon, Variable Conductance, Binary Mixture

چکیده در این مقاله، عملکرد دائم یک لوله حرارت ترموسیفون دارای مخلوطی از دو مبرد R11 و R113 به عنوان سیال عامل مورد بررسی قرار گرفته است. معاملات ممنتوم، انرژی و پیوستگی بطور همزمان و با در نظر گرفتن تنش های عمودی محوری در جریان و با استفاده از خواص متوسط مخلوط بطور عددی حل شده و رفتار هدایت متغیر لوله مورد تجزیه و تحلیل قرار گرفته است. نتایج حاصل از این مدل با مدل های عددی و نتایج تجربی دیگر محققین مقایسه شده و نقاط ضعف و قوت مدل مورد بررسی قرار گرفته است. مدل حاضر می تواند در مطالعات بهینه سازی و طراحی لوله های ترموسیفون از نوع هدایت متغیر بکار برده شود.

1. INTRODUCTION

For the first time Katzof [1] noted that small amounts of non-condensable gas can provide a simple thermostatic control for heat pipes. Since then, extensive efforts have been done for better understanding of gas loaded device performance and creating their useful constant temperature behavior. With gas loading, increasing the power input raises the system pressure, which compresses the non-condensable gas accumulated at the end of the condenser. This leads to an increase in condenser surface area and controls the evaporator temperature increase [2-5].

Recently Hijikata et al. [6] found that a similar variable conductance behavior could occur in reflux thermosyphons, even without non-condensable

gases, when the thermosyphon evaporator is charged with a liquid pool of R113 and R11. With this binary mixture, a shut-off zone was observed at the end of the condenser, as illustrated schematically by Figure 1(a). By this binary mixture, one can increase and decrease the shut-off zone by decreasing and increasing the input power to the evaporator, respectively. It is important to note that this variable conductance behavior is not extendable for all binary mixtures.

In one of the earliest studies of binary heat pipes, Tien and Rohani [7] presented some experimental results for a wicked heat pipe using water/ethanol mixture. They didn't observe constant pressure behavior, due to the evaporator geometry and non-ideal fluid combination. Thus

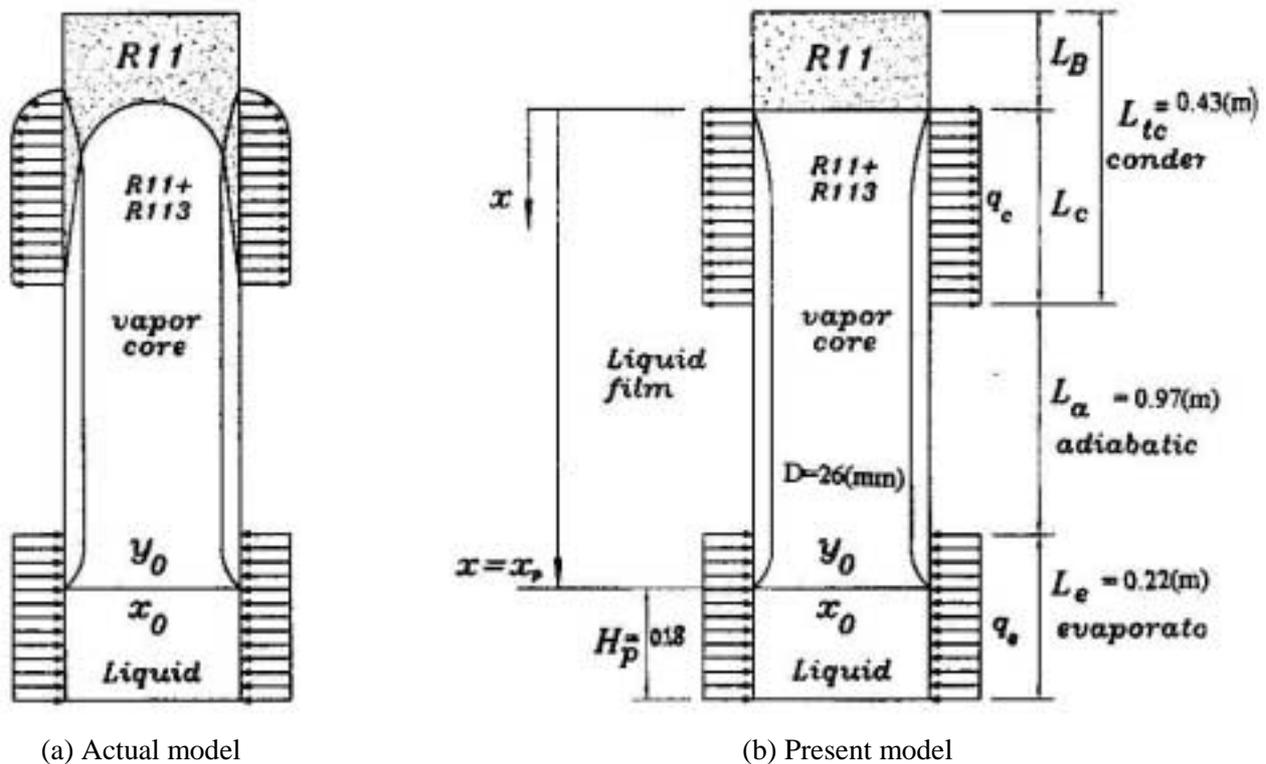


Figure 1. Theoretical modeling of thermosyphon.

their model did not account for the shut-off zone of the condenser. As illustrated in Figure 1(a), modeling of a two-phase closed thermosyphon requires a fundamental understanding of the following interrelated physical processes:

- Heat transmission through the evaporator wall.
- Boiling in the evaporator region (both liquid pool and liquid film).
- Condensation in the condenser region.
- Heat conduction through the condenser wall.
- Movement of the vapor core and the liquid film.

Compared with the wicked heat pipe, thermosyphon transients in wickless pipes occur much faster, because of the thermal response delay to heat transfer introduced by the wetted wick [6]. This is the main reason we used the wickless thermosyphon for the present analysis. Steady state performance of a variable conductance thermosyphon is the focus of this work.

A comprehensive model is developed from the basic conservation laws, and numerical techniques are developed to solve the nonlinear governing

equations.

The liquid-film momentum and normal stress, which have not been considered in previous studies, are included in this paper. From The results of this model, most operation parameters such as the mean vapor temperature, liquid film thickness, mass fluxes, as well as the operating limits (dry-out and flooding) associated with the steady state performance could be predicted. The predictions of the present model have been compared with numerical and experimental results of other investigators.

2. NUMERICAL MODEL AND MODEL ASSUMPTIONS

In the present numerical model Figure 1(b), the following assumptions used:

- The vapor and liquid flows are considered one dimensional, steady and Newtonian fluid.
- Compressibility of the vapor is negligible.

- The vapor and liquid binary mixture are in equilibrium on the phase equilibrium diagram as an ideal mixture (Raoult's law).
- Pressure drop in the liquid film is negligible.
- The axial conduction and the viscous dissipation are negligible.
- Concentration of the vapor from the top boiling pool surface till condenser entrance is nearly constant.
- Effect of diffusion at the interface of the two regions (effective and non-effective length of the condenser) is negligible.
- The film thickness, compared with the pipe radius is negligible. ($\delta/R \ll 1$).

3. CONTINUITY AND MOMENTUM EQUATIONS OF LIQUID FILM

The continuity and momentum equations of the liquid film could be written as:

$$\frac{d[(R^2 - r^2) u_L]}{dx} = 2RV \quad (1)$$

$$\rho_L \frac{d}{dx} [(R^2 - r^2) u_L^2] - \frac{d}{dx} \left[(R^2 - r^2) \frac{4}{3} \mu_L \frac{du_L}{dx} \right] - (R^2 - r^2) \rho_L g + 2r\tau_i + 2R\tau_w = 0 \quad (2)$$

In Equation 2, the first term corresponds to the total momentum change (including momentum advection) and the second term accounts for the axial normal stress in the liquid film. The final three terms corresponds to gravity, wall shear stress and interfacial shear stress, respectively. Unlike the pervious studies, the momentum advection contribution and the normal stress terms are included. Both of these terms affect thermosyphon performance. The normal stress term is also important in the numerical solution procedure.

The wall shear stress and the interfacial shear stress are modeled as:

$$\tau_w = \frac{1}{2} \rho_L u_L^2 C_{f_w} \quad \tau_i = \frac{1}{2} \rho_v (u_v + u_L)^2 C_{f_i} \quad (3)$$

where u_v and u_L are both positive in magnitude but opposite in direction. Friction coefficients could be written as [8]:

$$C_{f_w} = \frac{16}{Re_L} \text{ (Laminar liquid film, } Re_L < 2040) \quad (4)$$

$$C_{f_w} = 0.079 Re_L^{-1/4} \text{ (Turbulent liquid film, } Re_L > 2040) \quad (5)$$

$$C_{f_i} = \frac{16}{Re_L} \frac{\psi}{e^\psi - 1} \text{ (Laminar vapor core, } Re_L < 2040) \quad (6)$$

where ψ is a correction factor accounting for the effects of phase change [8]:

$$\psi = - \rho_L \frac{VR}{4\mu_v}$$

$$C_{f_i} = \frac{Re_{ev}^{0.33}}{1525} \text{ (Transition region } 2040 < Re_{ev} < 4000) \quad (7)$$

$$C_{f_i} = 0.05 + X_1 \left(\frac{\delta}{R} \right)^{X_2} \text{ (Turbulent vapor core } Re_{ev} \geq 4000) \quad (8)$$

$$\text{where } X_1 = 0.2574 \left(\frac{BO}{2} \right)^{X_2} 10^{\left(\frac{9.07}{BO} \right)} \text{ and}$$

$$X_2 = 1.63 + \frac{4.74}{BO}.$$

4. MASS AND ENERGY EQUATIONS FOR LIQUID FILM AND VAPOR

Assuming that the conduction and convection heat transfer at the liquid-vapor interface inside the thermosyphon are much smaller than the transport of latent heat from phase change, the energy equation for liquid film flow could be written as:

$$V = \frac{\dot{q}''}{\rho_L h_{fg}} = \frac{h(T_s - T_w)}{h_{fg} \rho_L} \quad (9)$$

where the film heat transfer coefficient from energy balance is defined as [8]:

$$h = \frac{K_L (T_i - T_w)}{\delta(T_s - T_w)} \quad (\text{Laminar, } Re_l \leq 2040) \quad (10)$$

$$h = \frac{0.056 R_{cl}^{-\frac{1}{5}} P_r^{\frac{1}{3}} K_L}{\left(\frac{v_L^2}{g}\right)^{\frac{1}{3}}} \quad (\text{Turbulent, } Re_l > 2040) \quad (11)$$

For the upward vapor core flow, the continuity equation can be written as:

$$\rho_v \frac{d(r^2 u_v)}{dx} = \rho_L 2RV \quad (12)$$

Combining Equation 12 with the Equation 1, one can write:

$$\rho_L \frac{d[(R^2 - r^2)u_L]}{dx} = \rho_v \frac{d(r^2 u_v)}{dx} \quad (13)$$

or in integrated form:

$$\rho_L (R^2 - r^2)u_L = \rho_v r^2 u_v \quad (14)$$

During steady-state operation, the relationship in Equation 14 implies that the downward mass flow rate of liquid film equals the upward mass flow rate at each cross section of the thermosyphon. From the Equation 14, the vapor core velocity can be evaluated as:

$$u_v = \frac{\rho_L}{\rho_v} \left(\frac{R^2 - r^2}{r^2} \right) u_L \quad (15)$$

Due to the assumptions made so far, it is not necessary to include momentum and energy equations for the vapor core. For the liquid pool surface, the continuity and energy equations are:

$$\rho_L (R^2 - r_p^2) u_{LP} = \rho_v r_p^2 u_{vp} \quad (16)$$

$$\dot{q}_e'' (2RH_p) = \rho_v r_p^2 u_{vp} h_{fg} \quad (17)$$

Equation 16 and 17 imply that the mass and energy flowing into the liquid pool are equal to those flowing out of the liquid pool.

The boundary conditions for u_L and r are as follows:

- At the top end of the thermosyphon, ($x = 0$):

$$r = R, \quad u_L = 0 \quad (18)$$

- At the liquid pool surface ($x = x_p$), from Equations 16 and 17 one can write:

$$\rho_L [R - r_p^2] u_{LP} = \frac{\dot{q}_e'' (2RH_p)}{h_{fg}} \quad (19)$$

In addition to these basic equations and boundary conditions, relations for the overall conservation of mass and energy in the entire thermosyphon system are also needed for calculating the liquid pool depth and determining the mean vapor temperature. The respective equations are:

$$M = \pi R^2 H_p \rho_L + \int_0^{x_p} [\pi r^2 \rho_v + \pi (R^2 - r^2) \rho_L] dx \quad (20)$$

$$\int_0^{x_e} h(T_s - T_{wc}) dx = \int_{x_a}^{x_e} h(T_{wc} - T_s) dx \quad (21)$$

where the heat transfer h in the liquid pool is modeled as [8]:

$$h = \frac{0.32 \rho_L^{0.65} K_L^{0.3} C_p^{0.7} g^{0.2}}{\rho_v^{0.25} h_{fg}^{0.4} \mu_L^{0.1}} \left(\frac{P}{P_{atm}} \right) (\dot{q}_e'')^{0.4} \quad (22)$$

By use of phase equilibrium diagram, Raoult's law and vapor pressure curve of each component, the mass fraction of the liquid pool and vapor core are calculated as follows [9]:

$$x_{R11} = \left[\frac{P - P_B}{P_A - P_B} \right] F \quad (23)$$

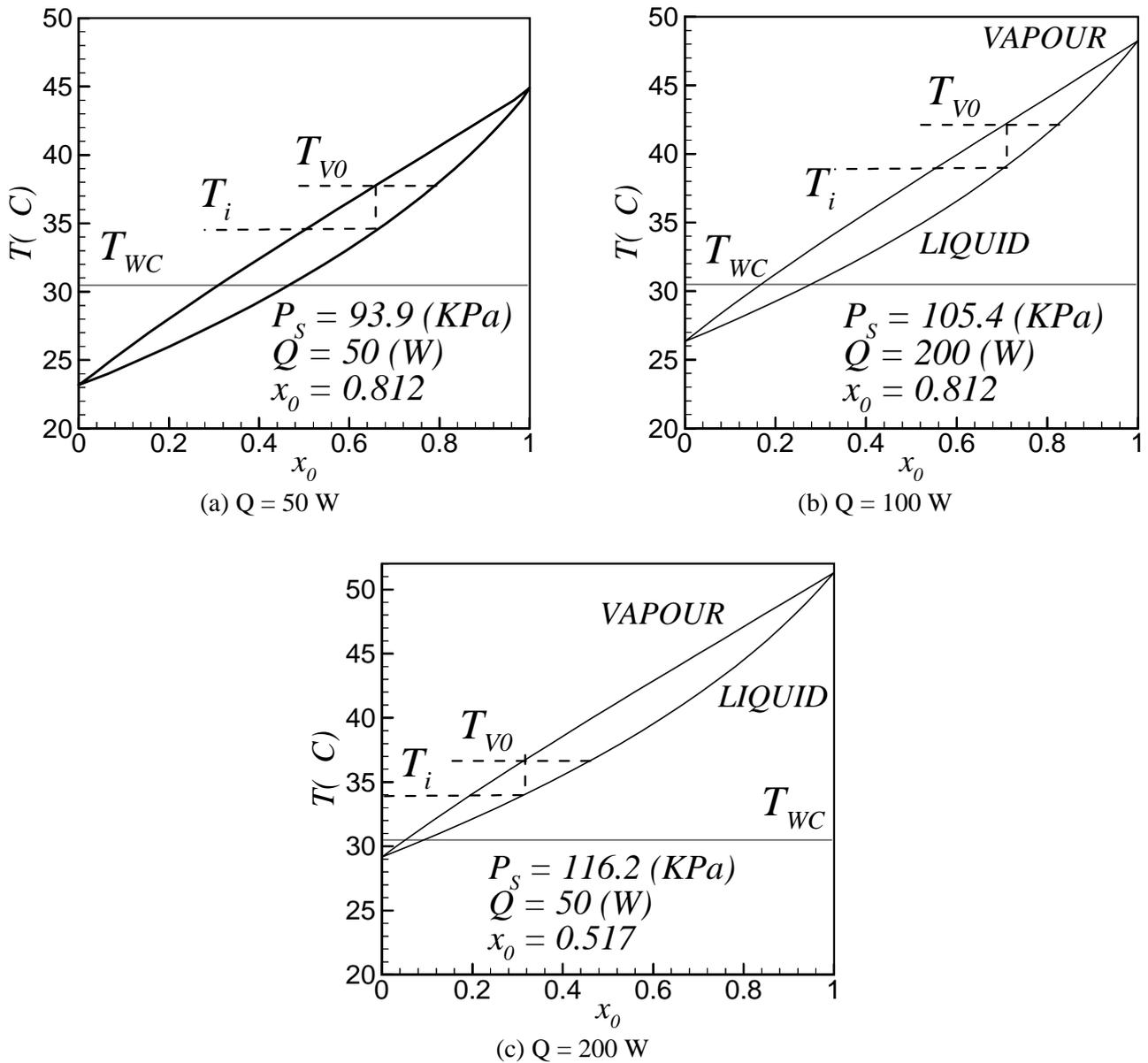


Figure 2. The relationship between temperature and mass concentration in phase equilibrium diagram.

$$y_{R11} = \left[\frac{P_A X_{R11}}{P} \right] F \quad (24)$$

where F is the ratio of the molecular weight of R11 to mixture molecular weight.

In Figure 2 a typical phase equilibrium diagram based on mass fraction of R₁₁₃ is shown.

5. CONDENSER EFFECTIVE LENGTH

As illustrated in Figure 1(b), the present model is based on the separation of the non-condensable region (more volatile component), from the active region of the condenser. This is the reason of neglecting the diffusion of two components at the boundary of the two regions. By this assumption, effective condenser length is approximated as:

$$L_{\text{ceff}} = L_{\text{tc}} - L_{\text{B}} \quad (25)$$

where L_{B} is the length occupied by the more volatile component, which in steady state conditions acts as a blocked length for exchanging the heat at condenser.

The mixture vapor of R11+ R113 with vapor concentration of y_0 enters to the condenser zone. With decreasing mixture temperature, it becomes liquid at the interface temperature and total pressure (P_s). In this way, concentration of more volatile component increases and it accumulates at the interface and the end of the condenser as a blocked length (Figure 1(a)).

In the present model we have assumed that the entire more volatile component (non-condensable) is stored at non-effective length of the condenser (L_{B}) as shown in Figure 1(b).

6. NUMERICAL SOLUTION METHOD

Before solving the momentum and energy equations, mean vapor temperature and system pressure are assumed known. Then using the vapor pressure table for each component and Raoult's law, the mass concentration in liquid (x_0) and vapor (y_0) are calculated. Continuity and momentum equations have been discretized by use of finite difference scheme, on an orthogonal grid.

By a known value of pool depth of liquid and assuming the values of non-effective length of the condenser, condenser temperature and evaporator temperature, starting from the first effective point of condenser ($u_L = 0$), momentum and energy equations are solved for the velocity at the second point.

The mean velocity of the vapor is calculated by use of Equation 15, Re_L , Re_v , and drag coefficients (C_{fi} , C_{fv}) are calculated by Equation 20. From the above results, wall and interface shear stresses are found. Finally after substitution of the above five terms in Equation 20, by increasing or decreasing the film thickness (for condenser or evaporator) satisfaction of Equation 2, (sum of terms must be zero) is checked. Knowing the film thickness of the first point and assumption of film thickness for

next point the procedure is continued till final point at the end of condenser. Finally the first guess of non-effective length at end of condenser is checked by use of Equation 14. Along the adiabatic length, film thickness of the liquid, film velocity and vapor core velocities are constant. The foregoing procedure is repeated for evaporator section by reduction of the film thickness. By calculation of heat of each element along the condenser, total heat removal from condenser (or input to evaporator) is found and by use of film and pool boiling heat transfer coefficients, balance of Equation 21 is checked. If the desirable balance didn't satisfy, the procedure will be repeated by changing the mean temperature of the vapor. After balance of energy Equation 21, the real amount of pool depth (H_p) is checked by use of Equation 19. If the difference between the first guess and the calculated pool depth becomes more than five percent, the program starts again with a new guess calculating the vapor mass, liquid mass and total mass of the mixture. The following equation is used for determining the average interface temperature along the condenser:

$$\bar{x}_i \Big|_{T=T_i} = y_0 \Big|_{P=P_s} \quad (26)$$

In all calculations, the mean property of the mixture based on mass percent of liquid and vapor is applied. This model can also predict two important operating limits such as dry-out and flooding.

During the program execution one must note that the first guessed values must not lead to the flooding on interface and dry-out in the evaporator. Physically, flooding implies that the local shear stress on the liquid film is larger than the gravitational force.

The resulting net upward force retards the downward liquid-film flow and results in an unstable flow pattern.

As expected, the solution accuracy of a larger grid size (such as $dx = 0.1\text{m}$) is not as good as that of a smaller grid size; however, the trend is still predicted well. The results from a large grid size calculation could also be used as the initial values for more precise calculations. For the numerical results presented, a grid size of $dx = 0.01$ (m) is chosen.

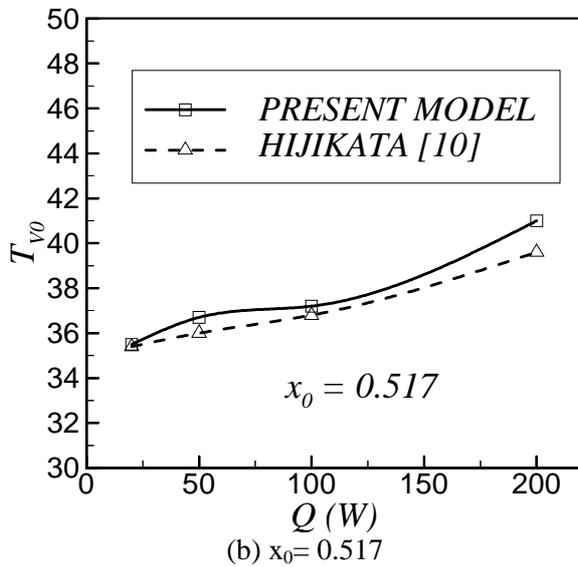
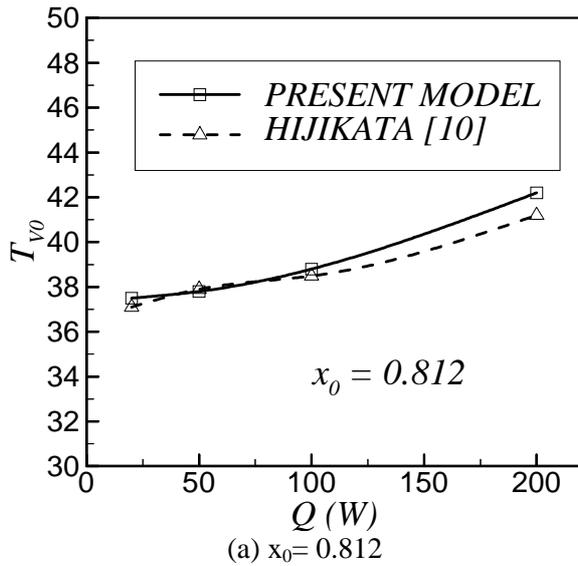


Figure 3. Variation of non-condensable length with temperature.

7. COMPARISONS AND DISCUSSION OF RESULTS

The relationship between the temperature and concentration is shown in the phase equilibrium diagram (Figure 2) where T_i denotes the average interfacial temperature weighted by condensation mass flux. y_0 and x_0 are specified at the saturated concentration. x_i is nearly equal to y_0 because the vapor that enters the cooling section condenses

completely. Raoult's law has been applied for calculating the results shown in this figure.

Therefore the maximum temperature difference in the vapor phase ($T_{v0}-T_i$), is roughly given by the temperature difference between the saturated vapor and liquid line at y_0 . Typical equilibrium diagrams for four conditions are shown in Figures 2(a, b, c).

Mean vapor temperature and block length (occupied by R11) are shown in Figure 3(a, b).

As expected, by increasing the pressure (or inlet vapor temperature), non-effective block length is reduced and for the values of power more than 100 (watt) this length is nearly zero.

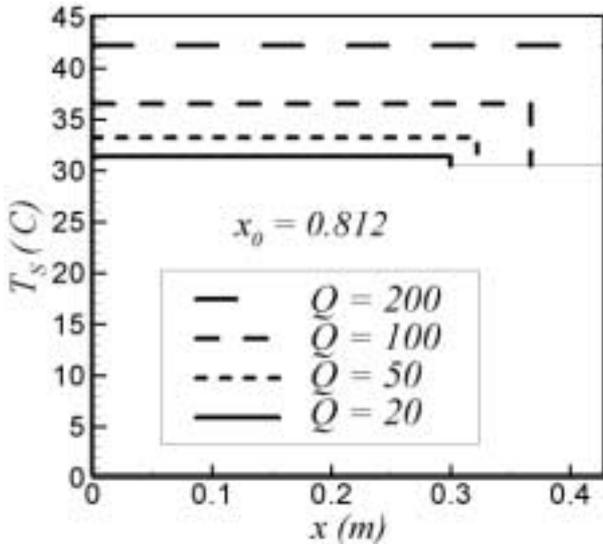
Results for two different liquid concentrations, namely 0.812 and 0.512 are shown In Figures 4(a, b). Inlet temperature of vapor versus power of the thermosyphon pipe for these two concentrations are shown and compared with Hijiakta numerical model [10].

As shown in the diagram of, Figure 4(a) at high concentrations, agreement between the two models is better in comparison with the low concentration. In Figure 4(b) this effect is shown clearly.

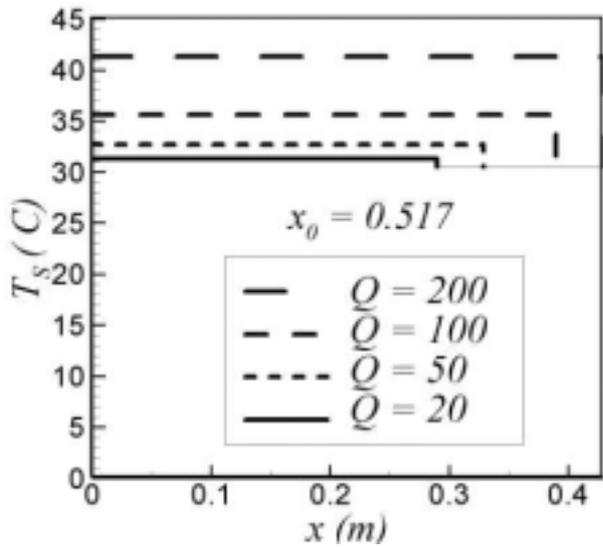
One must note that in all power levels, the prediction of the present model has a steady temperature higher than Hijiakata numerical model [10]. This is due to the absence of diffusion between the interface of active and non-active lengths and neglecting of heat exchanged between the two zones. This effect will be dominant with increasing the power and therefore we have a higher steady pipe temperature.

By increasing the inlet vapor temperature, effect of diffusion will be negligible because the system pressure reduces the block length, but in low inlet vapor temperature this effect will be very important (Figure 5).

For powers more than 50(w), the non-effective length that calculated by this model has a relatively good agreement with HIJIKATA model [10]. At low power the difference between the two models is relatively high. Finally, the calculated results are compared with the previous experimental result [10]. Figure 6(a) shows the comparison of the overall temperature difference in the cooling section, ($T_{v0}-T_{wc}$), in which the theoretical values for the condensation of pure vapor (R113 and R11) are also shown by dotted lines. Although the agreement between the present analysis and experimental results is not perfect, the constant



(a) $x_0 = 0.812$



(b) $x_0 = 0.517$

Figure 4. A comparison between two numerical models.

temperature behavior in the case of binary mixture is well predicted when compared to the condensation of pure vapors.

In addition, the predicted system pressure of present analysis agrees with other experimental and numerical results [10] as shown in Figure 6(b). Effect of diffusion at high concentration leads to an

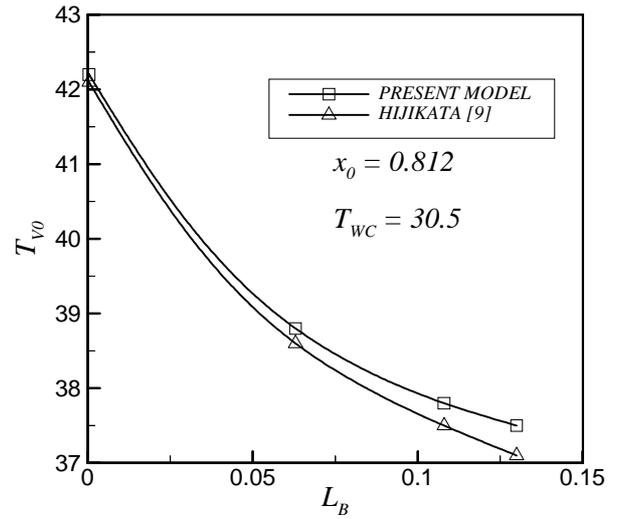
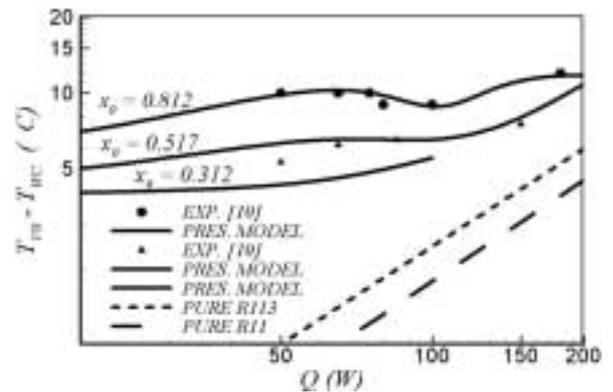
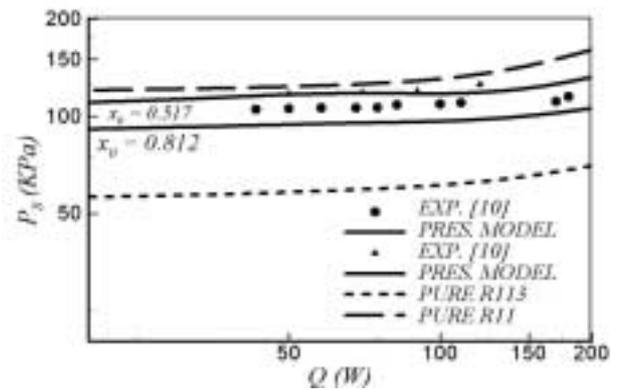


Figure 5. Variation of vapor temperature versus non-effective length.



(a) Overall temperature difference



(b) System pressure

Figure 6. Comparison with experimental results.

increase in effective condenser surface area and the related temperature difference reduction shown in the figure.

The present analysis neglects such detailed aspects as the effect of interfacial waves on liquid film, turbulence in the inlet vapor flow, and the distribution of velocity, temperature and concentration in the inlet vapor due to the existence of adiabatic section. These effects should be incorporated for more accurate analysis, however, the present model gives an understanding of the essential features of condensation phenomena in the cooling and heating sections. It also provides a practical method of prediction, to a certain degree of accuracy without requiring the detailed information on flow structures to be available

8. CONCLUSIONS

Condensation heat transfer in the cooling and heating sections of a binary heat pipe was analyzed numerically, and the following conclusions were obtained:

1. In the case of large heat loads, condensation occurs in the whole cooling section, in which case the vapor inlet temperature increases with increasing in heat load, which corresponds to an increase in the system pressure.
2. In the case of small heat loads, a non-condensing region appears which its length changes with a variation of heat load. In this case blocked condenser length, and the limiting temperature difference in the phase equilibrium diagram give the lower limit of the overall temperature difference, resulting in a constant temperature behavior.
3. Although the present analysis could predict the experimental data, further developments should be made to include the effects of diffusion at the interface of effective and non-effective lengths in cooling section.

9. NOMENCLATURE

Bo Bond number $(4\rho_l g R^2 / \sigma)$
 C_f Friction Coefficient

C_{PL} Liquid specific heat
 dx Grid size
 F Ratio of molecular weights (M_{R11} / M_{mix})
 g Gravitational acceleration
 h Heat transfer coefficient
 h_{fg} Latent heat of vaporization
 H_P Depth of liquid pool
 K_L Liquid thermal conductivity
 L Length of thermosyphon
 M Total amount of working fluid
 P Partial pressure
 P_S Total pressure of system
 Pr Liquid Prandtl number
 \dot{q}'' Wall heat flux
 Q Power of Pipe
 R Inner radius of thermosyphon
 r Vapor core radius
 Re Reynolds number $(4\Gamma / \mu)$
 T Temperature
 T_S Saturated temperature
 u Velocity
 V Vapor condensation
 x Axial distance from the top of
 y Vapor mass concentration

Greek Symbols

Γ Liquid mass flow rate per meter
 δ^* Liquid film thickness
 μ Dynamic viscosity
 ν Kinematic viscosity
 ρ Density
 σ Liquid surface tension
 τ Shear stress
 ψ Phase change correction factor

Subscripts

a Adiabatic region
atm Atmospheric inside the thermosyphon
c Condenser region
e Evaporator region
i Phase interface
L Liquid phase
P Liquid pool surface
 L_c Total length of condenser
S Saturation
w Tube wall
V Vapor phase
Eff Effective length of condenser

t Total
 A More volatile component (R11) velocity, volume
 B Less volatile component (R113)
 0 Pool condition the liquid film, liquid mass concentration

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