



An Efficient Secret Sharing-based Storage System for Cloud-based Internet of Things

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ABSTRACT

Internet of things (IoTs) is the newfound information architecture based on the internet that develops interactions between objects and services in a secure and reliable environment. As the availability of smart devices rises, secure and scalable mass storage systems for aggregate data is required in IoT systems. In this paper, we propose a new method for storing aggregate data in IoT systems by the use of threshold secret sharing scheme in the cloud storage. In this method, original data is divided into t shares at each block is considered as a share. The edge server does not send these shares (blocks) through the secure channel) to cloud service providers (CSPs). Rather, the edge server hides shares (blocks) with XORing two secret values and publishes the result. Indeed, with this method, CSPs has an amount of block information. This scheme is also verifiable, i.e., in the verification phase each CSP can verify its quasi-share. Moreover, before data retrieval, the edge server checks the consistency of provided quasi-share from CSPs of an authorized group. Also, the proposed scheme is since new data can be inserted or part of the original data can be deleted, without changing the shares. It is worth noting that the proposed scheme is more efficient compared with the other schemes since heavy and complex computation is not required.

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1. INTRODUCTION

The concept of the internet of things was first introduced by Ashton [1] in 1999. He describes a world in which everything has its own digital identity and allows computers to manage them. The most important feature of IoTs is the ability to connect various types of objects to the virtual world.

The model of IoTs and its standards have been reviewed and surveyed in several literature studies [2-8]. Miraz et al. [5] discussed the the Internet of Things (IoT), Internet of Everything (IoE), and Internet of Nano Things (IoNTs). They have distinguished the difference between IoTs and IoE which are wrongly considered to be the same by many people. Moreover, Lin et al. [4], first explore the relationship between Cyber-Physical Systems (CPS) and IoTs. Then they present existing architectures, enabling technologies, and security and privacy issues in IoTs to enhance the understanding of the state of the art IoTs development.

The challenges in IoTs have been addressed in several studies. Andra et al. [9] presented security vulnerabilities and challenges in IoTs and explored the security requirements for IoTs and provided a classification of the security challenges in IoTs systems using a new unique classification method consisting of four classes of attacks: physical, network, software, and encryption attacks. Moreover, Botta et al. [10] presented the integration of cloud computing and IoTs. In addition, Samuel [6] reviewed connectivity challenges in the IoTs-smart home. Also Wei et al. [11] presented survey work on the challenges issues and opportunities in IoTs. Generally, the IoTs system requires confidentiality, integrity, authentication and access control. Privacy and access control are also the major challenges of IoTs [12].

As the availability of many smart devices rises, fast and easy access to data as well as sharing more information is felt. Moreover, secure and scalable mass storage systems for aggregate data are required in IoT applications [4]. Mollah et al. [13] proposed a new

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cryptographic scheme that smart devices can share data securely with others at the edge of cloud-assisted IoTs with checking the integrity of decrypted data in data sharing and downloading phase. Furthermore, they proposed data-searching scheme to search desired data/shared data by authorized users on storage where all data are in encrypted form.

One of the methods used in the IoTs is to employ the secret sharing scheme [14]. A secret sharing scheme is designed to safeguard a secret by splitting it into shares and distributing them among a group of participants. In 1979, (t, n) -threshold secret sharing schemes were proposed by Blackley [15] and Shamir [16], independently. In a (t, n) -threshold secret sharing scheme, a secret can be shared among n participants such that t or more participants can reconstruct the secret, but $t - 1$ or fewer participants can not share it.

To adapt the IoTs applications, a cloud service provider offers rapid access to flexible, low-cost resources. Cloud computing is the most cost-effective method for utilization, protection, and upgrading the program and data. The advantage of using cloud computing is the almost unlimited storage space. Therefore, there is no need to concern about possible space shortages and to increase storage space. Also, since the information is stored in the cloud, preparing a backup version and restoring the information is much easier than storing the same information on a physical device. Therefore, most cloud service providers compete for data retrieval.

Asadi and Hamidi [17] point to the privacy issues of big data distributed in the cloud computing and analyze the privacy issue with the Petri model. Chen et al. [18] and Shen et al. [19] used the revised Blackley's and Shamir's secret sharing schemes, respectively, in a secure distributed file system. Then, Jiang et al. [14] proposed a secure and scalable storage system for aggregate data in IoTs, using the method proposed by Shen et al. [19]. Jiang et al. [14] introduced big data with M bytes which was divided into blocks with $T - 1$ bytes for storage. Then, for each block, a polynomial of degree $T - 1$ is generated, and each byte of each block is considered as a coefficient of a polynomial. Moreover, in this scheme, new data can be inserted, or part of the original data can be deleted, without changing shares.

In this paper, we proposed a new scheme based on the method Jiang et al. [14] for storing aggregate data in IoTs in cloud storage. In this scheme, we use a (t, n) -threshold secret sharing scheme. Our proposed scheme has the following properties:

1. The edge server divides the data into t blocks, and each block is considered as a share. However, the edge server does not send these shares (blocks) directly (through the secure channel) to $CSPs$, but the shares are generated by published information.

2. The correctness of published information about $CSPs$ can be verified by $CSPs$ in the verification phase.
3. In the data retrieval phase, before the data retrieval, the correctness of provided information by t $CSPs$ checked by the edge server. Thus, the edge server can prevent the cheating of some malicious $CSPs$.
4. The edge server is responsible for receiving, sharing and retrieving data. However, if the security of the edge server is compromised, then t $CSPs$ can retrieve the data in collaboration with each other and with the information, they had.
5. The new data can be inserted or part of original data can be deleted, without changing shares.
6. We have only simple and easy calculations of the hash function, and we only use " \oplus " (bitwise exclusive OR) and " \parallel " (concatenation) operators in the calculations. These operators make our scheme less costly and more efficient than other schemes [13, 14].

The rest of the paper is structured in the following sections: in section 2 we provide some definitions. In section 3, we propose the new method for storing aggregate data of IoTs applications in cloud storage. Section 4 involves analyzing the proposed method. In this section, we will describe some of the features and performance of the proposed scheme. Finally, section 5 concludes our paper.

2. PRELIMINARIES

2.1. Overall System Architecture **Data owner**

The data owner is the possessor of the sensitive data that he/she wants to store his/her data in the cloud storage environment. He/she registers in the cloud account and uploads his/her data by PC or laptop or smart devices. Then, whenever necessary, he/she will be able to access the data by requesting the data in his/her cloud account.

Edge server This part of the cloud receives data from the data owner and, for storing it, divides the data into shares by the secret sharing scheme. We do not have absolute trust in this party, which means that the edge server may be misled in generating and publishing values.

Cloud Service Provider (CSP) This party receives a share from the edge server. The $CSPs$ of an authorized subset send their shares to the edge server for retrieving the data. We do not have trust in this party, which means that this party maybe sends an invalid share to the edge server in the data retrieval phase.

Bulletin Board (BB) One of CSP is considered as a bulletin board, which public values published in it. We suppose that only the edge server can publish the values on the bulletin board, and only it can change the values

on the bulletin board, and the other (*CSPs*) can only view the published values.

2. 2. Security Properties **Correctness** If edge server and *CSPs* act honestly, the data retrieve by shares of any authorized subset of *CSPs*.

Verifiability Each *CSP* must be able to check the accuracy of its share. Furthermore, before retrieving data, the edge server must be able to verify the accuracy of the shares received by the *CSPs* in order to prevent the cheating of *CSPs*.

Secrecy The basic requirement is that an adversary cannot learn any information about the data, or it is impossible for any collusion of less than t *CSPs* to obtain any information about the data.

2. 3. Cryptographic Method We say that hash function H is cryptographically secure if H satisfies the following conditions:

- The hash function should be preimage resistant, i.e., for a given output y of H , it should be difficult to find a message m such that $y = H(m)$.
- The hash function should be second preimage resistant, i.e., for a given m_1 , it should be difficult to find a message $m_2 \neq m_1$ such that $H(m_2) = H(m_1)$.
- The hash function should be collision resistant, i.e., it should be difficult to find two different messages m_1 and m_2 such that $H(m_1) = H(m_2)$.

The difficulty of finding a collision depends on the size of the hash value.

2. 4. Threat Model **Insider threats** Malicious insiders such as *CSPs* that want to access/disclose/modify the stored data.

Outsider threats Outside intruders are those who want to access the data, alone or with the collaboration of some unauthorized subsets of *CSPs*.

3. THE PROPOSED SCHEME

In this section, we describe our proposed scheme. We need some notations and values in Table 1.

In the proposed scheme, we assume that each *CSP_i* has ID_{1i}, ID_{2i} which receives them with $\{ID'_{2i}\}_{CA} = H(ID_{2i})$ from *CA* (certificate authority). Also, *CA* sends ID_{1i} to the edge server.

The steps of the proposed scheme are as follows:

- **Submitting the data**
 - **Registration**

As shown in Figure 1, the data owner selects a username and registers her/his information. Then, he/she receives a password (note that the data owner can change the password).

TABLE 1. The notations used in the proposed scheme

Notation	Meaning
D	Data
N	The size of data D
n	The number of cloud service providers (<i>CSPs</i>)
t	The threshold of <i>CSPs</i>
m	The size of t blocks of data D
$H(\cdot)$	The secure hash function
$\{0, 1\}^*$	The set of all binary strings of arbitrary finite bit length
$\{0, 1\}^q$	The set of all binary strings of fixed length q
\bar{D}	The hash value of the data D
CSP_i	The i^{th} cloud service provider
B_i	The i^{th} block with size q
w	The number of authorized groups
\parallel	Concatenation
\oplus	Bitwise exclusive OR operator
\bar{B}_{ij}	The hash value of (Block $i \parallel j$)
\bar{D}	The hash value of data D
d_i	The quasi share of CSP_i
\hat{d}_j	The public value
v_{ij}	The public value (value of masked \bar{B}_{ij})
H_j	The hash value of $d_1 \parallel d_2 \parallel \dots \parallel d_t \parallel j$
s_{ij}	The public value (value of masked block B_i)
T	The chosen randomly value by the edge server
I_i	The hash value of $T \parallel ID_{1i} \parallel ID_{2i}$
\tilde{d}_i	The value of masked quasi-share d_i
d'_i	The hash value of quasi-share d_i

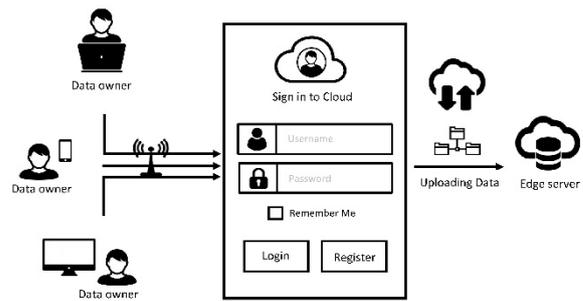


Figure 1. Registration and submission of data by the data owner

- **Login and submitting**

1. The data owner logs into a nearby edge server from a smart device using the username and password and submits the data S .
2. The data owner also submits some related keywords of the data such that any authorized recipient users are allowed to view to find the data. In this case, the

data owner can introduce some users to access data. There are two cases when users of the group want to access the data using keywords:

- Users of the group are authorized to access the data. In this case, authorized users request the data by providing keywords. Then, the edge server provides the data to them.
- The data owner revokes access of some users to the data in the group. In this case, the data owner revokes access of some users (U_i) by providing (ID_i , keywords, Neg) to the edge server (note that we assume Neg is a sign of revocation of access to the data). Once, when the user U_i requests the data by providing the keyword, the edge server checks the user U_i access to the data. In this case, the edge server will display “unauthorized access” to the user U_i .

• **Construction**

1. After submitting the data D by the data owner, the edge server first publishes an access structure $\Gamma = \{A_1, A_2, \dots, A_w\}$ on the BB , where A_j ($j = 1, 2, \dots, w$) is an authorized group. Then, the edge server splits the data into t blocks with size m . If $t \nmid |Data|$, then the edge server appends the randomly generated padding strings to the end of the data such that $t \mid |Data \parallel padding|$.
2. Suppose $|D| = |Data| = N$ or $|D| = |Data \parallel padding| = N$ and $t \mid N$. So

$$D = \overbrace{a_{11}a_{12} \dots a_{1m} \parallel a_{21}a_{22} \dots a_{2m} \parallel \dots \parallel a_{t1}a_{t2} \dots a_{tm}}^N$$

Block 1: $a_{11}a_{12} \dots a_{1m}$

Block 2: $a_{21}a_{22} \dots a_{2m}$

⋮

Block t : $a_{t1}a_{t2} \dots a_{tm}$

3. The edge server chooses a secure hash function $H: \{0,1\}^* \rightarrow \{0,1\}^q$ and computes

$$\bar{D} = H(D) \tag{1}$$

4. Now, the edge server acts based on the following cases:

- **If $|Block\ i| < q$**

1. The edge server appends the randomly generated padding strings to the end of each block such that the length of the block equals to q .

$$B_i = Block\ i \parallel padding\ i, \quad i = 1, 2, \dots, t \tag{2}$$

$$\Rightarrow |B_i| = q$$

$$\bar{B}_{ij} = H(Block\ i \parallel j) \tag{3}$$

2. Each CSP_i sends $\mathcal{J}D_i = ID_{1i} \oplus ID_{2i}, \{ID'_{2i}\}_{CA}$ to the edge server. The edge server first obtains $ID_{2i} =$

$\mathcal{J}D_i \oplus ID_{1i}, ID'_{2i} = H(ID_{2i})$ and then compares ID'_{2i} with $\{ID'_{2i}\}_{CA}$. If two hash values are equal, then the edge server accepts ID_{2i} , otherwise rejects it. After this, the edge server obtains for every CSP_i in an authorized group A_j

$$\forall d_1, d_2, \dots, d_n \in \{0, 1\}^q, \exists \hat{d}_j \in \{0, 1\}^q \text{ s.t.} \tag{4}$$

$$\bar{D} = \bigoplus_{csp_i \in A_j} d_i \oplus \hat{d}_j \tag{5}$$

$$v_{ij} = \bar{B}_{ij} \oplus \bar{D} \tag{6}$$

$$H_j = H(d_1 \parallel d_2 \parallel \dots \parallel d_t \parallel j) \tag{7}$$

$$s_{ij} = B_i \oplus \bar{B}_{ij} \oplus H_j \tag{8}$$

$$I_i = H(T \parallel ID_{1i} \parallel ID_{2i}), \quad T \in_R \{0, 1\}^q \tag{9}$$

$$\tilde{d}_i = d_i \oplus I_i \tag{10}$$

$$d'_i = H(d_i) \tag{10}$$

where $i = 1, 2, \dots, t, j = 1, 2, \dots, w$.

3. The edge server sends \tilde{d}_i to CSP_i and publishes $T, \hat{d}_j, d'_i, v_{ij}, s_{ij}$, and Hash function H on the BB (T, \hat{d}_j, d'_i for CSP_i and v_{ij}, s_{ij} for itself). Indeed, each CSP_i just gets d_i as quasi-share and in the Verification phase, it just needs to verify the validity of d_i . Then, the edge server stores the size of paddings.

Figure 2 shows the construction phase of the proposed scheme.

- **If $|Block\ i| = q$ or $|Block\ i| = kq$**

1. In case $|Block\ i| = q$, it is not necessary to perform the padding for Block i in Eq. (2).
2. In case $|Block\ i| = kq$, the edge server considers

$$k\bar{B}_{ij} = \overbrace{\bar{B}_{ij} \parallel \bar{B}_{ij} \parallel \dots \parallel \bar{B}_{ij}}^k. \tag{11}$$

Similar to Equation (11), the edge server considers $k\bar{D}, kH_{ij}$ instead of \bar{D}, H_{ij} . Then, the edge server performs the rest of the calculation in the same way as the case $|Block\ i| < q$.

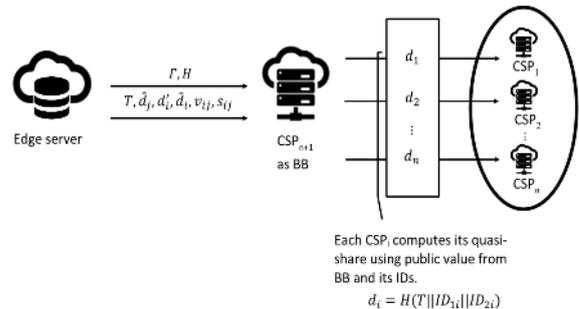


Figure 2. The Construction phase of the proposed scheme

- **If |Block i | > q**
Suppose

$$(k - 1)q < |\text{Block } i| < kq.$$

Note that the size of the block here is greater than q and is not divisible by q . In this case, the edge server performs as follows:

$$\forall i = 1, 2, \dots, t \quad B_i = \text{Block } i || \text{padding } i \quad (12)$$

s.t. $|B_i| = kq$

Then, the edge server performs the rest of the calculation in the same way as case $|\text{Block } i| = kq$.

- **Verification**

Each CSP_i computes

$$I_i = H(T || ID_{1i} || ID_{2i}),$$

$$d_i = \tilde{d}_i \oplus I_i$$

$$d_i'' = H(d_i)$$

and then checks

$$d_i'' \stackrel{?}{=} d_i'. \quad (13)$$

If Equality (13) holds, the published hash value d_i' is valid. Otherwise d_i' is invalid.

After successful verification, the edge server deletes $ID_{2i}, i = 1, 2, \dots, n$.

- **Data requesting and retrieval**

We only show data retrieval for the first case where $|\text{Block } i| < q$, and the two remaining cases are similarly obtained.

1. If data owner requests the data (or an authorized user requests the data by searching keywords), then $CSPs$ of an authorized group j provide their quasi-shares to edge server.
2. After sending t quasi-shares d_i by CSP_i ($i = 1, 2, \dots, t$), the edge server obtains and checks

$$d_i'' = H(d_i) \quad (14)$$

$$d_i'' \stackrel{?}{=} d_i'. \quad (15)$$

The edge server accepts quasi-share d_i , if Equality (15) holds, and rejects it otherwise.

3. After accepting t quasi-shares, the edge server computes

$$\bar{D} = \bigoplus_{CSP_i \in A_j} d_i \oplus \hat{d}_j \quad (16)$$

$$\bar{B}_{ij} = v_{ij} \oplus \bar{D} \quad (17)$$

$$H_j = H(d_1 || d_2 || \dots || d_t || j) \quad (18)$$

$$B_i = s_{ij} \oplus \bar{B}_{ij} \oplus H_j. \quad (19)$$

Then, the edge server appends the obtained blocks together for retrieval.

Figure 3 shows the Data retrieval phase of the proposed scheme.

- **Inserting new data**

Suppose that there is new data to be added to the original data. So, there are four cases:

1. **Inserting new data before Block 1**

The new discrete block(s) is/are generated. There are three cases:

- If

$$|\text{new data}| < |\text{Block } 1|,$$

then the edge server randomly appends a new padding to the new data block such that

$$|\text{new data} || \text{padding}| = m.$$

- If

$$|\text{new data}| = |\text{Block } 1|,$$

then the edge server considers the new data as the new block of size m .

- If

$$|\text{new data}| > |\text{Block } 1|,$$

then the edge server splits the new data into blocks of size m . If

$$|\text{last generated new block}| < |\text{Block } 1|,$$

then the edge server randomly appends a new padding in the same way as the first instance.

In general, in this case, there are more than t blocks. Therefore, at least $t + 1$ $CSPs$ can retrieve data.

2. **Inserting new data between Block i data**

The edge server splits the Block i with inserted data into new blocks of size m . If

$$|\text{last generated new block}| < |\text{Block } i|,$$

then the edge server randomly appends a new padding in the same way as the first instance of the previous case.

3. **Inserting new data between Block i and Block $i + 1$**

The new discrete block(s) is/are generated similar to case 1.

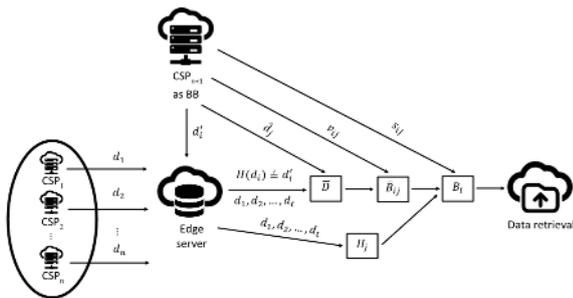


Figure 3. Data retrieval phase of proposed scheme

4. Inserting new data after the last Block

The new discrete block(s) is/are generated similar to case 1.

- **Deleting part of the data**

Suppose that part of data is deleted. So, there will be three cases.

1. **Deleted data is just part of Block i ; $|\text{deleted data}| < |\text{Block } i|$**

In this case, the edge server performs the padding again only for the block that part of its data has been deleted.

2. **Deleted data is part of Block i and Block $i + 1$; $|\text{deleted data}| < |\text{Block } i, \text{Block } i + 1|$**

In this case, the edge server performs the padding again only for Block i and Block $i + 1$.

3. **$|\text{deleted data}| > |\text{Block } i|$**

In this case, less than t blocks remain. So, the deleted block(s) should be generated. If the number of deleted Blocks $< |\text{Block } i|$, then the edge server selects an adjacent block of deleted data and splits it into blocks of size 1. Note that

$$1 \leq |\text{last generated new Block}| < m.$$

Then, edge server appends padding to the newly generated blocks. Now, if

$$\text{the number of deleted Blocks} > |\text{Block } i|,$$

then the edge server selects several adjacent blocks of deleted data for splitting and generates new blocks instead of deleted blocks similar before.

4. ANALYSIS OF OUR PROPOSAL

4. 1. Security Analysis In this section, we will analyze the features of our proposal.

Theorem 4.1. *Any collusion of less than t CSPs cannot obtain any information about the data.*

Proof. Without loss of generality, suppose $CSP_1, CSP_2, \dots, CSP_{t-1}$ (malicious insiders) with quasi-shares d_1, d_2, \dots, d_{t-1} , respectively, intend to retrieve the data without CSP_t . To do this, malicious insiders should obtain blocks B_1, B_2, \dots, B_t . However, to obtain these blocks, they need values \bar{B}_{ij}, H_j , which values \bar{B}_{ij}, H_j are derived from Equations (5) and (6), respectively. That is, they must first obtain the quasi-share d_t . Malicious insiders can try to derive quasi-share of CSP_t by published value d'_i in the construction phase. Since the hash function H is one-way, they cannot obtain the quasi-share d_t from public information d'_i .

Theorem 4.2. *The edge server cannot cheat by publishing invalid values in the Construction phase. Indeed, its cheating is detectable.*

Proof According to the verification phase, if the edge server publishes invalid d'_i , then Equality (13) does not hold. Indeed, since the hash function H is second preimage resistant, the edge server cannot find the second preimage \bar{d}_i such that $d'_i = H(\bar{d}_i) = H(d_i)$. Moreover, since values v_{ij}, s_{ij} are required for data retrieval, so the edge server must publish valid values of v_{ij}, s_{ij} in the construction phase. Otherwise, in the data retrieval phase, the original data will not be restored, and this will be the edge server error. ■

Theorem 4.3. *If some malicious CSPs provide fake shares to prevent retrieval of the main data, then their cheating is detectable.*

Proof According to the data retrieval phase, if CSP_i provides invalid quasi-share d_i , similar to proof of Theorem 4.2, Equality (15) does not hold. ■

Theorem 4.4. *Under the secure hash function, outside intruders cannot get any information about the data.*

Proof Suppose outside intruders want to achieve blocks of data by public information $T, \hat{d}_j, d'_i, v_{ij}, s_{ij}$. But, according to proof of Theorem 4.1, outside intruders need to get a quasi-shares of t CSPs to get blocks and retrieve the original data. But since H is a one-way function, they can not get t quasi-shares and retrieve data using public values d'_i . ■

Remark Our proposal is scalable because we can add new data or delete part of the original data without changing all the shares. When inserting new data, previous shares don't change and only some new shares are generated. Also, when part of the original data is deleted, only some of the blocks are affected by the deletion of the data that are subject to change.

4. 2. Performance Analysis In this section, in Tables 2 and 3, we consider two schemes for comparison with our scheme. One of the reported schemes [13] is based on the cryptographic mechanisms and the other [14] is based on the secret sharing scheme.

The scheme introduced by Mollah [13] used RSA and AES cryptosystems. Since the computational complexity of the RSA encryption is $O(n^3)$, the computational complexity of the scheme becomes $O(n^3)$ (It is notable that the symmetric cryptosystem AES has a much lower computational complexity, so we ignore it).

The scheme introduced by Jiang et al. [14] splits the data into several blocks such that for each block, a polynomial of degree $t - 1$ is formed. If we assume that

there are l blocks, then we have l polynomials. To retrieve data, each t shares together retrieves these l blocks and the scheme requires $O(lt^2)$ computations.

The proposed scheme is established based on the *XOR* operator, concatenation, and hash functions. The construction phase requires $O(t)$ computations since it consists of $(5w + 9)t + 3$ *XOR* operators, concatenations and hash function calls. The verification phase comprises of (n) *XOR* operators, $(2n)$ concatenations and calls the hash function (n) times. Therefore, it is accomplished in $O(n)$. Similarly, the data retrieval phase comprises of $(2t)$ *XOR* operators, (t) concatenations and calls the hash function (t) times. Therefore it is accomplished in $O(t)$.

4. 3. Experimental Evaluations We implemented and compared the runtime of the proposed method and the technique introduced by Jiang et al. [14]. In both experiments, the same 10000 secret messages each of length 70 bytes are sent to participants (*CSPs*) and reconstructed using t shares. Each experiment is repeated 10 times and the average required time per message is measured. Figure 4 shows the results of the methods for $t = 3, 4, 5, 6, 7, 8, 9$. The methods are implemented in C#.Net on a regular PC with an Intel G3220 3.0 GHz CPU and Windows 10 operating system. The results

confirm the effectiveness of the proposed method in all cases. This performance gain is the result of using hash functions and simple operators such as XOR and concatenation instead of heavy matrix or polynomial computations in finite fields. It is notable that the proposed method also includes the verification step that is not part of the technique defined by Jiang et al. [14].

5. CONCLUSION AND FUTURE WORK

In this paper, we proposed a new verifiable and scalable cloud storage for aggregate data in IoTs. In this scheme, the edge server divided the data into t blocks and each block was considered as a share. But these blocks were hidden for each *CSP*. Indeed, the edge server obtained a quasi-share for each *CSP* and published the hash value of it. Then in the data retrieval phase, the edge server retrieved the blocks of data by quasi-share of *CSPs* of an authorized group. In the verification phase, each *CSP* obtained the hash value of its quasi-share and compared it with published hash value by the edge server to observe whether the valid hash value has been published to it by the edge server. Moreover, before data retrieval, the edge server checked the correctness of provided quasi-shares by t *CSPs*. Therefore, the fault of *CSPs* in providing invalid quasi-shares was detectable. Since blocks of data are hidden using the quasi-shares, the confidentiality of data is maintained. Thus, this scheme is safe against attacks of malicious insiders and outsiders. Also, in our scheme, new data can be inserted or part of the original data can be deleted, without changing all shares. Furthermore, we showed that our scheme is more efficient than some other schemes because, in this scheme, we had only simple and easy calculations of the hash function, and we only used “ \oplus ” (bitwise exclusive OR) and “ $||$ ” (concatenation) operators in the calculations.

TABLE 2. Comparisons between the proposed scheme with other related schemes

Feature	Ref. [13]	Ref. [14]	Our scheme
Data privacy	Yes	Yes	Yes
Data availability	Yes	Yes	Yes
Verifiability	No	No	Yes
Data scalability	No	Yes	Yes
Resist cheating by dishonest <i>CSPs</i>	Yes	No	Yes
Type of cloud	Single cloud	Multi-cloud	Multi-cloud
Method used	AES and RSA	Polynomial	Hash-based Secret sharing
Need secure channel	No	Yes	No
Have public value	No	No	Yes

TABLE 3. Comparison of computational complexity

Feature	Ref. [13]	Ref. [14]	Our scheme
Construction	$O(n^3)$	$O(ln)$	$O(t)$
Verification	—	—	$O(n)$
Retrieval	$O(n^3)$	$O(lt^2)$	$O(t)$

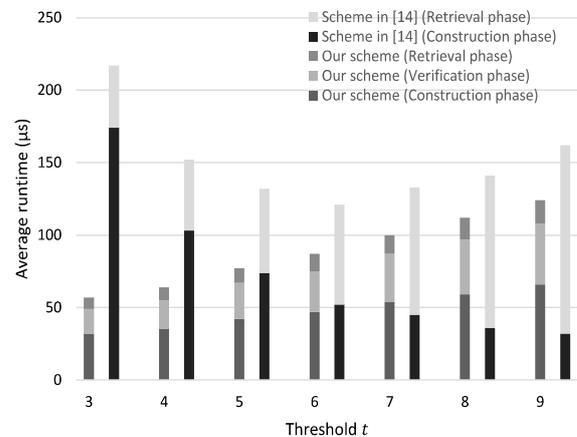


Figure 4. The execution time of our scheme compared to the scheme introduced by Jiang et al. [14]

In this paper, we proposed a scheme in which the edge server is trusted. But in the real world, the server may not be absolutely reliable. In this way, it can exploit user information and documents. So, we are looking to propose a scheme in which the edge server and CSPs are not reliable, and the user's file and information in cloud environments are stored in such a way that the servers and CSPs do not access its content in any way.

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An Efficient Secret Sharing-based Storage System for Cloud-based Internet of Things

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اینترنت اشیاء، معماری اطلاعات نوظهور مبتنی بر اینترنت است که تعاملات بین اشیاء و سرویس‌ها (خدمات) را در یک محیط امن و قابل اطمینان توسعه می‌دهد. چون دسترسی زیاد دستگاه‌های هوشمند روبه افزایش است، سیستم‌های ذخیره‌سازی انبوه امن و مقیاس‌پذیر برای داده‌های جمع شده در برنامه‌های IoTs مورد نیاز است. در این مقاله، یک روش جدید برای ذخیره‌سازی داده‌های جمع‌شده در IoTs با استفاده از تسهیم راز آستانه‌ای (t, n) در ذخیره‌سازی ابر پیشنهاد می‌کنیم. در این روش، داده اصلی به t بلوک تقسیم می‌شود طوری که هر بلوک به‌عنوان یک سهم در نظر گرفته می‌شود. سرور لبه این سهم‌ها (بلوک‌ها) را به‌طور مستقیم (از طریق کانال خصوصی) برای سرویس‌های ارائه‌دهنده خدمات (CSPها) ارسال نمی‌کند. بلکه سرور لبه این سهم‌ها (بلوک‌ها) را با XOR کردن با دو مقدار مخفی، پنهان می‌کند و مقدار بدست‌آمده را منتشر می‌کند. در واقع با این روش، هیچ یک از CSPها اطلاعاتی درباره بلوک‌ها ندارد. این طرح همچنین تأییدپذیر است. یعنی، در مرحله تأییدپذیری، هر CSP می‌تواند درستی شبه‌سهم خود را تأیید کند. بعلاوه، قبل از بازیابی داده، سرور لبه درستی شبه‌سهم‌های ارائه شده توسط CSPها را بررسی می‌کند. همچنین طرح پیشنهادی مقیاس‌پذیر است، چون، بدون تغییر دادن سهام، می‌توان داده جدید اضافه و یا بخشی از داده اصلی را حذف کرد. قابل توجه است که طرح پیشنهادی در مقایسه با طرح‌های دیگر کارآمدتر است، زیرا محاسبات سنگین و پیچیده مورد نیاز نیست.

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