

A CONTINUOUS PLANE MODEL TO MACHINE LAYOUT PROBLEMS CONSIDERING PICK-UP AND DROP-OFF POINTS: AN EVOLUTIONARY ALGORITHM

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Abstract One of the well-known evolutionary algorithms inspired by biological evolution is genetic algorithm (GA) that is employed as a robust and global optimization tool to search for the best or near-optimal solution with the search space. In this paper, this algorithm is used to solve unequal-sized machines (or intra-cell) layout problems considering pick-up and drop-off (input/output) points. Such problems may be formulated as a continuous plane model that is applicable to cellular manufacturing systems. The aim is to assign all the machines to the related locations within the floor plan in such a way that an objective function, as the total material handling is optimized while satisfying all the constraints. In this paper, a GA methodology is used to generate promising and feasible layout solutions and to find the best or near-optimal solution searched within the space problem. For this purpose, a new genetic presentation and genetic operators are designed. Finally, computational results reported by the GA program and a construction algorithm are presented in the context of the test problems. In addition to the above objective function, the dead space ratio of final layout solution is calculated for each test problem.

Key Words Machine/Cell Layout Problems, Mathematical Programming Models, Pick-Up/Drop-Off Points, Evolutionary Algorithms

چکیده الگوریتم ژنتیک یکی از بهترین الگوریتم‌هایی است که با بکارگیری تکامل زیستی می‌تواند مسایل بهینه سازی را حل کند. یکی از این مسایل مربوط به استقرار ماشین‌ها یا سلول‌های دارای اندازه غیر یکسان و با در نظر گرفتن نقاط گذاشت و برداشت (ورودی و خروجی) می‌باشد. در این مقاله، یک مدل ریاضی صفحه پیوسته ارائه شده است که در سیستم‌های تولید سلولی کاربرد دارد. هدف این است که کلیه ماشین‌ها در مکان‌های مربوطه استقرار یابند به نحوی که تابع هدف آن یعنی هزینه حمل و نقل، حداقل گردد. همچنین در این مقاله، حل‌های مختلفی از استقرار ماشین‌ها با استفاده از الگوریتم ژنتیک پیشنهادی ارائه و بهترین حل گزارش می‌شود. در ضمن طراحی خاصی از کدینگ و اپراتورهای ژنتیک ارائه می‌گردد. در خاتمه چندین مساله مورد ارزیابی قرار می‌گیرد و حل آنها با یک روش ساختاری مقایسه می‌شود. علاوه بر تابع هدف فوق، نسبت فضای مرده برای حل استقرار نهایی محاسبه می‌گردد.

1. INTRODUCTION

Early researchers in facilities layout problems (FLPs) believed that the best approach to find good solutions was through the development of a model as a quadratic assignment problem (QAP) [1]. Its objective is to minimize the material handling costs incurred by the material flow between each of the paired facilities and distance between each of the paired locations. Demand requirements and

process routes for given part types may be used to generate the elements of the flow matrix. These data are required for the QAP model. The distance matrix is constructed according to the pre-determined location configuration of the given FLP. Therefore, there are n equal-sized blocks representing n locations, where each equal-sized facility belongs to one block/location.

By using the QAP, facilities layout problems can be solved by using implicit enumeration (or

traditional optimization) approaches optimally in order to yield an exact solution. The exact solution is obtained in a reasonable computing time where the problem size is small, say 15 facilities, in a reasonable computational time [2]. It should be noted that the QAPLIB [3] reported that the modest size problems, say 20 facilities, is still considered as a computationally non-trivial task.

Because of the above limit, there is a great demand for good heuristics to solve layout problems with the size of greater than 20 facilities. Kusiak and Heragu [4] classified heuristic approaches in the following ways: construction, improvement, hybrid and graph-theoretic methods. There are no well-known deterministic approaches to solve those *NP*-hard problems optimally [5]. The QAP is a difficult problem belonging to a broader class of combinatorial optimization problems.

If there are changes in the flow data, then a flexible layout is needed which can be modeled as the QAP by defining a time period for each department. It is supposed that the existing layout is considered as a single-period (static) layout that incurs some costs. When a rearrangement of an existing layout occurs, then the problem known as a DLP is to determine a revised layout in different periods of time. Lacksonen and Ensore [6] proposed an algorithm using a modified cutting plane to solve the QAP form of the dynamic layout problem and mixed-integer linear programming to find the block diagram layout with varying department areas.

Kim *et al.* [7] proposed an algorithm based on a combination of a mixed-model scheduling, simulated annealing and graph-theoretic methods for assigning workers to machines in single and double-row layout considering the zone constraint (i.e., machines assigned to a worker are adjacently located). The model is mathematically formulated for both the slow period and the peak period, minimizing the variation of workloads and maximizing the preference of workers. Kouvelis *et al.*, [8] applied simulated annealing to the QAP with few zoning constraints resulting in a model called a restricted QAP. A number of equal-sized facilities layout solutions have been reported by genetic algorithms [9]. Krause and Nissen [10] compared six-test problems considering positive zoning constraints with different algorithms using

penalty functions and two multi-objective optimization approaches. A mathematical programming model has been applied by Tavakkoli-Moghaddam [11] to generate large-scale unequal-sized facilities layout solutions using genetic algorithms. In this model, the center-to-center rectilinear method has been used to measure the distance between each pair of facilities. The objective was to find the locations of the center coordinates of facilities (decision variables) so that the total flow-distance cost is minimized.

2. MATHEMATICAL PROGRAMMING MODELS

A mathematical programming model is presented to solve unequal-sized facilities layout problems considering the pick-up/drop-off (P/D) points, where the dimensions of the floor plan and each facility can be estimated. However the user may change the floor dimensions to generate alternative layouts. The P/D points are sometimes called input/output (I/O) (or loading/unloading) points. This mathematical model optimizes the objective function subject to constraints, which it finds of the P/D points of all the facilities (as decision variables) to represent a layout solution with respect to the configurations, which apply. Figure 1 helps to follow the notations used in the mathematical model. The reference coordinate is assumed to be the lower-left hand corner of the floor plan. Montreuil and Ratliff [12] proposed an algorithm to find the I/O locations of facilities based on a design skeleton obtained by the cut tree algorithm. Welgama and Gibson [13] presented a construction algorithm to solve the machine layout problem with P/D points, which was used as a test method for the steel industry.

The original mathematical model used to solve multi-row machine layout problems was first introduced as two-dimensional space allocation problems. Heragu and Kusiak [14] developed this model to solve double-row machine layout problems that can be formulated by a version of the QAP or a mixed-integer programming model. They considered the distance measured by the rectilinear method between the centers of each pair of machines. In Heragu and Kusiak's model, each

center point has an x coordinate and a y coordinate. The x and y -center coordinates of a machine assigned to the floor plan do not change if the machine rotates. Thus the related orientation of the machine is free if it does not violate any constraint that would apply to the mathematical model.

Instead of the above center coordinates of machines, one point for both pick-up (P) and drop-off (D) or two distinct P/D points are considered for all the machines to be assigned within the floor boundaries. The rectilinear distance between these P/D points determines the loading and unloading movements between each

pair of machines. Welgama and Gibson [13] presented an objective function considering the pick-up and drop-off points. For the simplicity of their model, they assumed that P/D points are located at the midpoint of each machine side parallel with the aisle. However, in the approach of this thesis, any P/D points can be manipulated. They can be anywhere within the perimeter of the rectangular shape of the given machine including its corners. These P/D points have two x and y -coordinates to be determined as decision variables, which contribute to the objective function.

$$\text{Min. } \sum_{i=1}^n \sum_{j=1}^n c_{ij} [f_{ij} (|xp_j - xd_i| + |yp_j - yd_i|) + f_{ji} (|xp_i - xd_j| + |yp_i - yd_j|)] \quad (1)$$

s.t.:

$$|xp_i - xd_j| \geq \frac{1}{2} (l_i + l_j) + ld_{ij} \quad \forall i, j \quad (2)$$

$$|yp_i - yd_j| \geq \frac{1}{2} (w_i + w_j) + hw_{ij} \quad \forall i, j \quad (3)$$

$$|xd_i - xp_j| \geq \frac{1}{2} (l_i + l_j) + ld_{ij} \quad \forall i, j \quad (4)$$

$$|yd_i - yp_j| \geq \frac{1}{2} (w_i + w_j) + wd_{ij} \quad \forall i, j \quad (5)$$

$$|x_i - x_j| \leq L - [\frac{1}{2} (l_i + l_j) + lc_i + lc_j] \quad \forall i, j \quad (6)$$

$$|y_i - y_j| \leq W - [\frac{1}{2} (w_i + w_j) + wc_i + wc_j] \quad \forall i, j \quad (7)$$

$$x_i - \frac{1}{2} l_i \leq xp_i \leq x_i + \frac{1}{2} l_i \quad \forall i \quad (8)$$

$$y_i - \frac{1}{2} w_i \leq yp_i \leq y_i + \frac{1}{2} w_i \quad \forall i \quad (9)$$

$$x_i - \frac{1}{2} l_i \leq xd_i \leq x_i + \frac{1}{2} l_i \quad \forall i \quad (10)$$

$$y_i - \frac{1}{2} w_i \leq yd_i \leq y_i + \frac{1}{2} w_i \quad \forall i \quad (11)$$

$$x_i, y_i, xp_i, yp_i, xd_i, yd_i \geq 0, \quad i = 1, 2, \dots, n \quad (12)$$

where,

n = number of machines

c_{ij} = cost per trip per unit distance between machines i and j

f_{ij} = material flow from machine i to machine j (forward moves for loading)

f_{ji} = material flow from machine j to machine i (backward moves for unloading)

xp_i and yp_i = x -coordinate and y -coordinate (location) of the pick-up point of machine i

xd_i and yd_i = x -coordinate and y -coordinate (location) of the drop-off point of machine i

x_i and y_i = x - and y -center coordinates of machine i respectively.

ld_{ij} and wd_{ij} = horizontal and vertical clearances between machines i and j respectively

lc_i and wc_i = horizontal and vertical clearances between machine i and the floor plan.

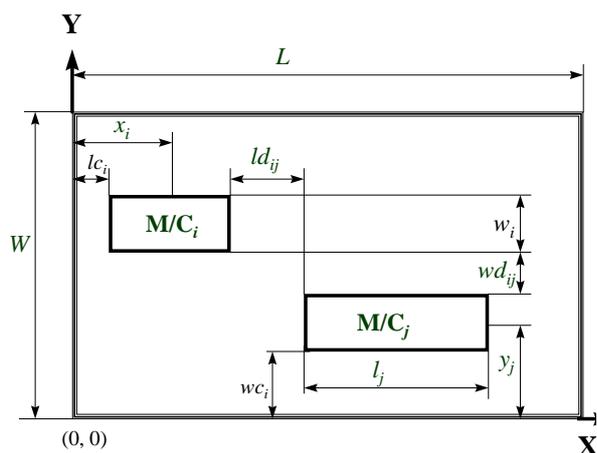


Figure 1. Schematic of machines layout.

It is assumed that all machines are square or rectangular shapes. If the shape of a machine is irregular, then the machine size is defined as a rectangular block. This block can be considered as one machine so that this machine can be fitted into one block. It is possible to include the clearance between each pair of machines or between a machine and the floor boundaries to the machine, as one block.

It is assumed that the cost per trip per unit distance between machines i and j is considered as unit one ($c_{ij} = 1$) in this thesis. The objective function (Equation 1) is used to find the location of machines, their configurations (vertical or horizontal positions) and orientation of pick-up and drop-off points so that the total material handling costs are minimized. Appropriate, lc_i and wc_i may be considered in order to give enough space for loading/unloading, maintenance, safety, material handling equipment and work-in-process (WIP) areas between machines and building boundaries while determining relative locations of machines. These clearances can be included in the dimensions of machines and must be satisfied in the constraints.

The first four constraints (Equations 2-5) ensure that there is no overlapping of machines and all machines are fitted within the floor boundaries. It should be noted that the non-overlapping condition is met if only two of the above constraints are satisfied. The next two constraints (Equations 6

and 7) ensure that all machines are located and fitted in the floor plan as well. Constraints in Equations 8-11 guarantee that the P/D points fall within the boundaries of a machine. The last set of constraints guarantee that the variables given in Equation 12 must be real and positive. Two test problems are taken from [13] assigning unequal-sized areas of 6 and 12 machines within the floor plan.

3. GENETIC ALGORITHMS

Genetic algorithms [16 and 17] evaluate a population of strings over a number of generations. There are several key issues that must be considered to enable one to solve any optimization problem using genetic algorithms. It is first necessary to define an appropriate genetic coding (representation) of a solution (ie., encoding of a phenotype to a genotype); a fitness function measure; genetic operators; the parameters to control the algorithm; and the criteria to terminate the algorithm. An appropriate design of genetic operators affects on the performance of genetic algorithms for facilities layout problems [18]. A general approach can be constructed using the following main steps:

1. Select a good representation (genetic encoding) to encode the search space.
2. Determine an appropriate fitness function and scaling method.
3. Find a selection scheme.
4. Choose and design genetic operators
5. Set the GA parameters to control and terminate the process.

3.1 Structure of Genetic Coding The standard genetic coding introduced by Holland [18] was in a binary format that is no longer suitable to accommodate facilities in relation to locations or floor plan. Therefore integer numbers are required in designing the genetic coding (genotype) representing a layout solution (phenotype). In the case of unequal-sized facilities layout problem, a chromosome is composed of a sequence of integers representing blocks of each

Generate (valid chromosome)

Read the GA parameters and input data.

do

Initialize (or set) all the chromosome bits to zero. Not all the facilities are processed.

Select a facility at random.

Assign the selected facility to the top-left corner of the available floor plan, either horizontally or vertically depending on how dimensions of the facility are stored in the input file.

Deduct the facility area from available space.

Allocate the facility number to the respective locations of the chromosome (this facility is now processed.)

for (1 to N , number of blocks)

if (the chromosome bit is zero) then

Select an unprocessed (new) facility at random.

if (the new selected facility neither exceeds the floor boundaries nor overlaps with another facility, ie. it does not violate the constraints.) then

Assign the new selected facility to the right of the previous facility assigned to the floor plan or to the new row of the floor plan (this facility is now processed.)

else if (the selected facility neither exceeds the floor boundaries nor overlaps with another facility, ie. it does not violate the constraints.) then

Assign the new selected facility to the right of the previous facility assigned to the floor plan or to the new row of the floor plan (it is now processed and rotated.)

else (the selected facility is not processed)

end if

end for

end do (till a valid chromosome is created, ie. all the facilities are assigned and processed)

Figure 2. A pseudo code to generate a valid chromosome in the initial population.

facility. It should be noted that each facility might occupy more than one block.

To solve the above problems using LADEGA, the genetic coding of a layout solution must be designed. LADEGA always generates valid chromosomes by satisfying all the constraints, which forms the chromosome. At the initial stage, all the chromosome bits are set to zero. Figure 2 shows a pseudo code for generating a valid chromosome.

To evaluate the quality of each layout solution,

a transformation of the chromosome (genotype) into the solution (phenotype) is required. The objective value computed must be transferred to the fitness value as LADEGA works on the fitness values.

3.2. Creation of the New Population A new population is generated from the current (old) population via reproduction (duplication), crossover and mutation operators. If the reproduction operator is applied, then an individual

(called parent) is selected from the current population based on the selection scheme and copied exactly to the new population. If the mutation operator is applied, then a selected individual, according to the selection scheme, is mutated and placed in the new population. In the case of crossover, two individuals are selected and crossed over in order to create two new individuals (called children). The process is repeated when the new population contains N new individuals, where N is the population size.

3.3. Design of Genetic Operators By using genetic operators new chromosomes are created in the next generation. The mutation operator is applied if the selected random number is equal to or less than the mutation rate defined by the user. In this case, a chromosome (a solution) is first selected according to a selection scheme, say tournament selection, and a facility is selected from the above chromosome. Then LADEGA tries to find another facility with the same dimensions and orientation. If the facility is found, then it is exchanged with the first facility selected. If no facility is found to be exchanged, then the process is repeated for a certain number of iterations, say 100, before it stops.

A new mutation operator is developed, in this paper, to change the position of the P/D points of a machine by rotating them 180 degrees relative to the existing machine chosen by the selection scheme. This rotation does not violate the non-overlapping condition. In this case, the locations of the P/D points are changed, not the orientation of the machine. This is always valid for any machine. The following paragraph describes the new GA operator used as a mutation operator. Firstly, a chromosome (parent) is selected based on the selection scheme from the current population. Secondly, an integer number from the interval (1, number of machines (i.e, n)) is randomly selected, which represents a machine to be mutated. Then, LADEGA rotates this machine by 180 degrees horizontally or vertically, depending on its orientation. Thus, the locations of the P/D points of this machine are changed. By doing this, a new layout solution is generated with a different objective value.

To apply a crossover operator, two chromosomes (parents) are first selected according

to the selection scheme. A few facilities are selected at random from the first parent and then they are copied to the same positions of the first new chromosome (offspring). Remaining facilities are obtained from the second parent in order without repeating the previously selected facility numbers. If LADEGA cannot create a new offspring, then a few facilities are selected at random from the first parent and the above process continues. This process is repeated for a certain number of iterations, say 100.

Two chromosomes (parents) are selected according to the selection method from the existing population. Then two crossing points are randomly chosen, between 1 and the number of machines, from the first parent. The machines between these points are copied into the new chromosome and LADEGA tries to orderly (sequentially) assign the remaining machines from the second parent, without any repeating machine number. If a valid chromosome has not been generated after a certain number of iterations (say 50), new crossing points are chosen from the first parent and the above process is repeated. Again, if no valid chromosome is obtained after a certain number of iterations (say 100), the selected chromosome (first parent) is exactly copied to the new population.

4. COMPUTATIONAL RESULTS

Two test problems, named Wel-6 and Wel-12, are taken from Welgama and Gibson [13]. A non-symmetric material flow matrix, machine dimensions and the fixed P/D points are used as the input data. The shape of each machine is assumed to be rectangular. An irregular shape is taken to be rectangular which envelops it. They proposed a construction algorithm to solve such problems. This algorithm does not incorporate the floor dimensions. The final layout generated is fitted into an enveloping block in order to calculate its dead space ratio (DSR). However, LADEGA [15] is an improved method, which requires the floor dimensions. These floor dimensions accommodate a certain number of standard (equal-sized) blocks showing the chromosome length. All 6 and 12 facilities of such problems

require 325 and 1469 standard blocks. This result shows that the sizes of some machines are very large.

A mathematical programming model, discussed in Section 2, is used to solve Wel-6 and Wel-12. Constraints incorporated in the above model may require the following input data: dimensions of machines, material flow between each pair of machines, location restrictions (fixed pre-location), dimensions of the floor plan, orientation of machines, clearance between machines, clearance between machine and floor boundaries, pick-up and drop-off (input/output) points of machines. Further constraints such as aisle structures; door locations; closeness rating known as a qualitative factor; time period involved in dynamic layout problems; and shortest path of material flow can be considered as further research projects.

The Model is the highly constrained formulation in which LADEGA handles the constraints by generating valid chromosomes, on which all constraints are met. The result of a valid chromosome is a feasible layout solution, i.e. all the facilities (machines) are assigned in the floor plan.

4.1. Orientation and P/D Points of Machines

Machines can be positioned either parallel to a building structure or at right angles to that position or horizontally/vertically in a graphical sense,

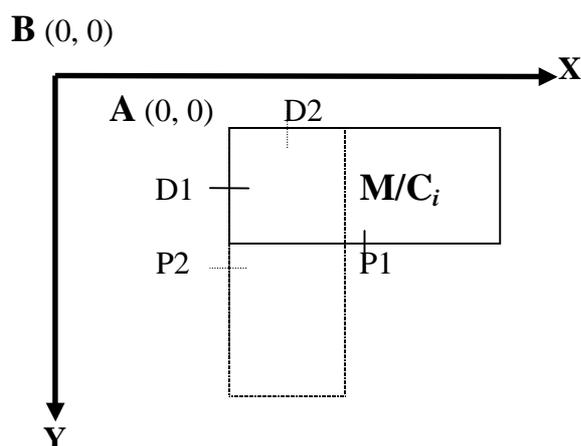


Figure 3. Locations of D1/P1 points (not rotated) and D2/P2 points (rotated) of machine i .

depending on the input data given for the dimensions of the machines. The first integer number read in the above input data is considered as the length of the facility and the second number as its width. Using this convention the length of a facility may be less than its width. A facility may rotate if a facility cannot be placed within the floor area. There are six different positions of P/D points for a machine [13].

4.2. The LADEGA Procedure Used for Wel-6 and Wel-12

There are usually two main components of most genetic algorithms that are problem dependent: the genetic coding and the fitness function. In order to design the former component, decision variables of a layout solution (phenotype) must be encoded into a chromosome, which is a sequence of integers representing facilities numbers to the related locations. The total integer numbers of a chromosome are equal to the total number of blocks, depending on the floor dimensions. As an example, the chromosome length will be 1500 ($= 60 \times 25$) if the floor dimensions are $W = 60$ by $L = 25$ for the Wel-12. This length implies that the computational time of LADEGA increases. It should be noted that the complexity of the above problem is equivalent to a layout problem of 1500 equal-sized facilities.

In LADEGA, however, a machine may be rotated (i.e. its orientation is changed) if it cannot be placed in its position or if it violates one of the constraints discussed in Section 2.2. The initial placement of a machine strongly depends on reading its dimension from the input data. It is not necessary to place a machine with longer sides horizontally. After assigning all the machines (i.e., creating a valid chromosome), LADEGA measures the rectilinear distances between P/D points of machines in order to evaluate the quality of the layout solution.

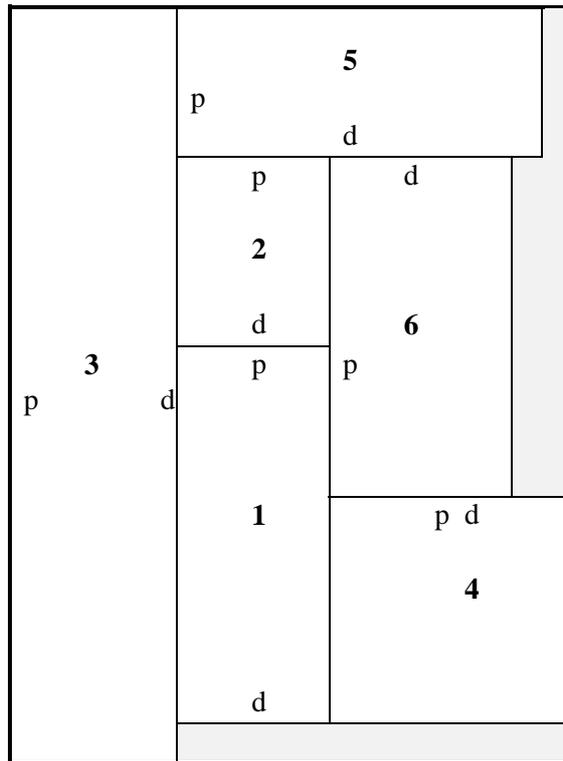
It should be noted that the fixed P/D points of machines, given in the input data, are based on the reference coordinates, relative to the bottom-left corner of each facility. However, LADEGA adjusts the coordinates of P/D points where the reference coordinates are at the top-left corner of the machines. Figure 3 shows the above reference coordinates "A". A machine can rotate 90 degree around the point "A" if it overlaps with another

TABLE 1. Comparison of Computational Results for the Wel-6 and Wel-12, Showing their Increased Performance in the Parenthesis, in Terms of Times.

Problem	Objective value		Dead space ratio		Performance ^b
	Construction ^a	LADEGA	Construction ^a	LADEGA	
Wel-6	421.5	565.5 (0.745)	0.370	0.097 (3.814)	197.26 %
Wel-12	7193.0	6655.5 (1.081)	0.100	0.021 (4.762)	255.34 %

a) Construction algorithm proposed by Welgama and Gibson [15].

b) Overall performance (%) of LADEGA in respect to the construction algorithm.

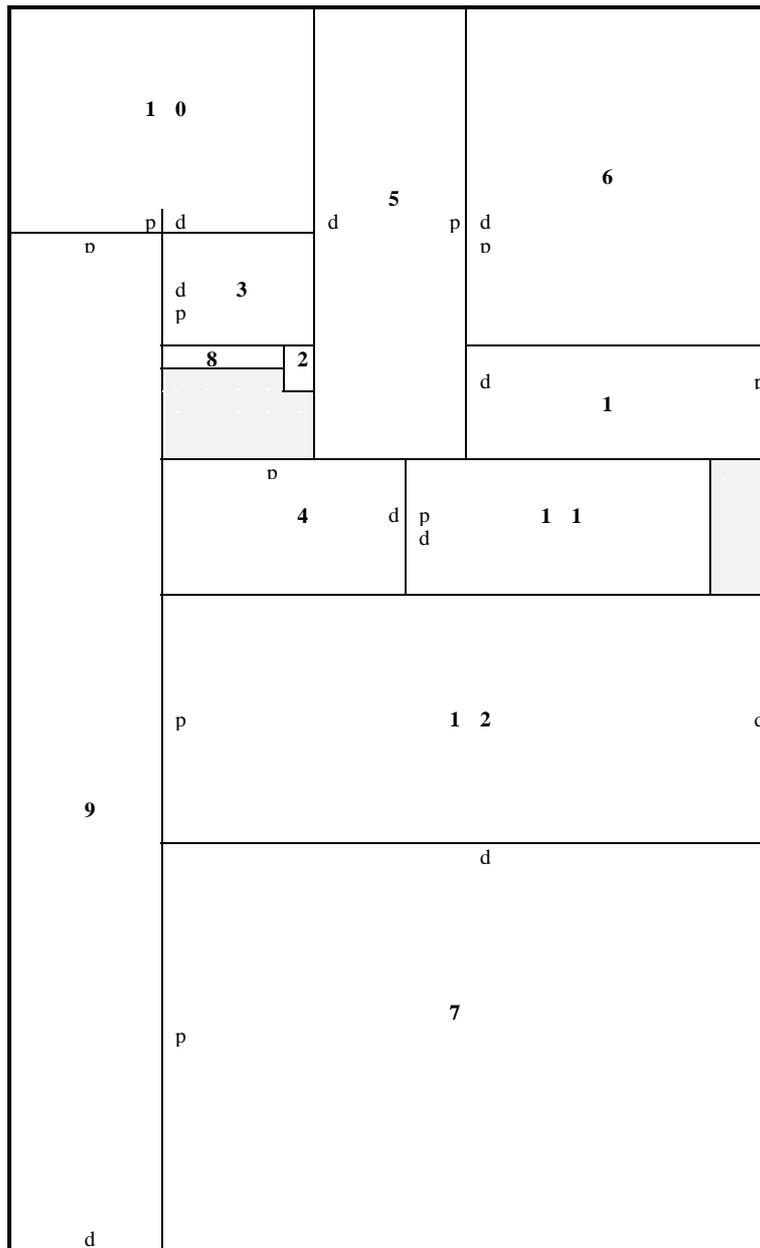


No.	1	2	3	4	5	6
X_p	7.5	7.5	0.0	14.0	5.0	10.0
Y_p	11.0	16.0	10.0	7.0	18.0	11.5
X_d	7.5	7.5	5.0	14.0	11.0	13.0
Y_d	1.0	11.0	10.0	7.0	16.0	16.0

Width =20, Length = 18, DSR = **0.097**

(x_p , y_p) and (x_d , y_d) = x and y -coordinates of pick-up and drop-off points respectively

Figure 4. Objective value of 565.5 and the related P/D points for the Wel-6 via applying a large population size, 1000.



No.	1	2	3	4	5	6	7	8	9	10	11	12
x_p	25.0	9.5	5.0	9.0	15.0	15.0	5.0	5.0	2.5	5.0	13.0	5.0
y_p	42.5	45.0	47.5	40.0	50.0	52.5	10.0	44.5	50.0	50.0	37.0	27.0
x_d	15.0	9.0	5.0	13.0	10.0	15.0	15.0	7.0	2.5	5.0	13.0	25.0
y_d	42.5	44.0	47.5	37.0	50.0	52.5	20.0	44.0	0.0	50.0	37.0	27.0

Width = 60, Length = 25, DSR = **0.021**
 (x_p, y_p) and $(x_d, y_d) = x$ and y -coordinates of pick-up and drop-off points respectively.

Figure 5. Objective value of 6655.5 and the related P/D points for the Wel-12 via applying a large population size, 1000.

facility. The reason is that LADEGA considers the point "B" as the reference coordinates of the floor plan and starts assigning a facility from this point to the right of the floor plan. If a machine rotates, then the new P/D points will be as P2 and D2 respectively.

To generate a valid chromosome, first a machine is randomly selected and assigned to the top-left corner of the floor plan. The assignment depends on the given dimensions of the machine defined as length (x) and width (y) respectively. Then, another machine is randomly selected and assigned to the right side of the machine assigned before. Thus, these two machines are adjacent to each other. A machine can be rotated if it overlaps with another machine either in the x direction or in the y direction, or if it exceeds the boundaries of the floor plan. Another machine is selected if the above two conditions are not satisfied.

4.2. Layout Solutions for Wel-6 and Wel-12

The 6-machines problem (Wel-6) has been taken from [13] with the fixed P/D points. This problem is solved by LADEGA. Nine different floor dimensions experimented give different layout solutions obtained in each case. However, the LADEGA program never converges if the floor dimensions of 17 by 20 are chosen. Because in the above problem, there are 325 equal-sized blocks (areas) in order to allocate all 6 machines.

The quality of the layout solution improves when a large population size, i.e. 1000, is used in LADEGA. In this case, the best objective value of 565.5 is found at generation 35 out of 50 with the DSR of 0.097. The associated layout solution and its P/D points are shown in Figure 4. The computational results are compared with the results reported by [13], as given in Table 1.

Welgama and Gibson [13] presented a machine layout solution of 7193 with the dead space ratio (DSR) of 0.1 for the Wel-12 using a construction algorithm. They pointed out that the weight for considering the dead space is 40%, which is incorporated in a bi-criteria objective function. It was not

possible to generate a layout solution with the DSR less than 0.1 using their algorithm. However, a better layout solution with the objective value of 6655.5 and a DSR of 0.021 ($W = 60$ and $L = 25$) has been found so far in this study, as shown in Figure 5. This solution indicates an increase in the solution quality by 7.5% (1.08 times better performance) while the space utilization is also improved by 79% (4.762 times better performance).

The total area required for all 12 machines is 1469. It should be noted that the total standard blocks within the floor dimensions must be greater than 1469. It should also be noted that either width or length of the floor plan must be greater than or equal to 50, due to the dimensions of machine 9 (50 by 5). Therefore only nine different tests varying the floor dimensions have been studied experimentally. It takes a few hours to search for the best layout solution. Among the layout solutions generated by LADEGA only one solution shows the objective value of 6655.5 with the dead space ratio of 0.021. Figure 6 relatively shows the test problem 8 has the low objective function value and low DSR.

Table 1 shows the comparison of the layout solution shown in Figure 5 and the solution taken in [13]. The changed (either increased or decreased) performance, measured by the size of the LADEGA's reports compared with other cases, is given in brackets in the Table 1. Welgama and Gibson [13] considered the weights of $\alpha = 0.6$ and $\beta = 0.4$ for the objective value and the dead space ratio respectively, where $\alpha + \beta = 1$. In solving the Wel-6, LADEGA performs 1.9726 times (in overall) better than the construction algorithm proposed by [13] when the above weights are included in a bi-criteria objective model.

For the Wel-12, LADEGA generates a layout solution that is 2.5534 times (in overall) better than the solution taken in [13]. This means that the total performance of the solution generated by LADEGA is 255.34% when the total performance of the solution reported in [13] is 100.0%.

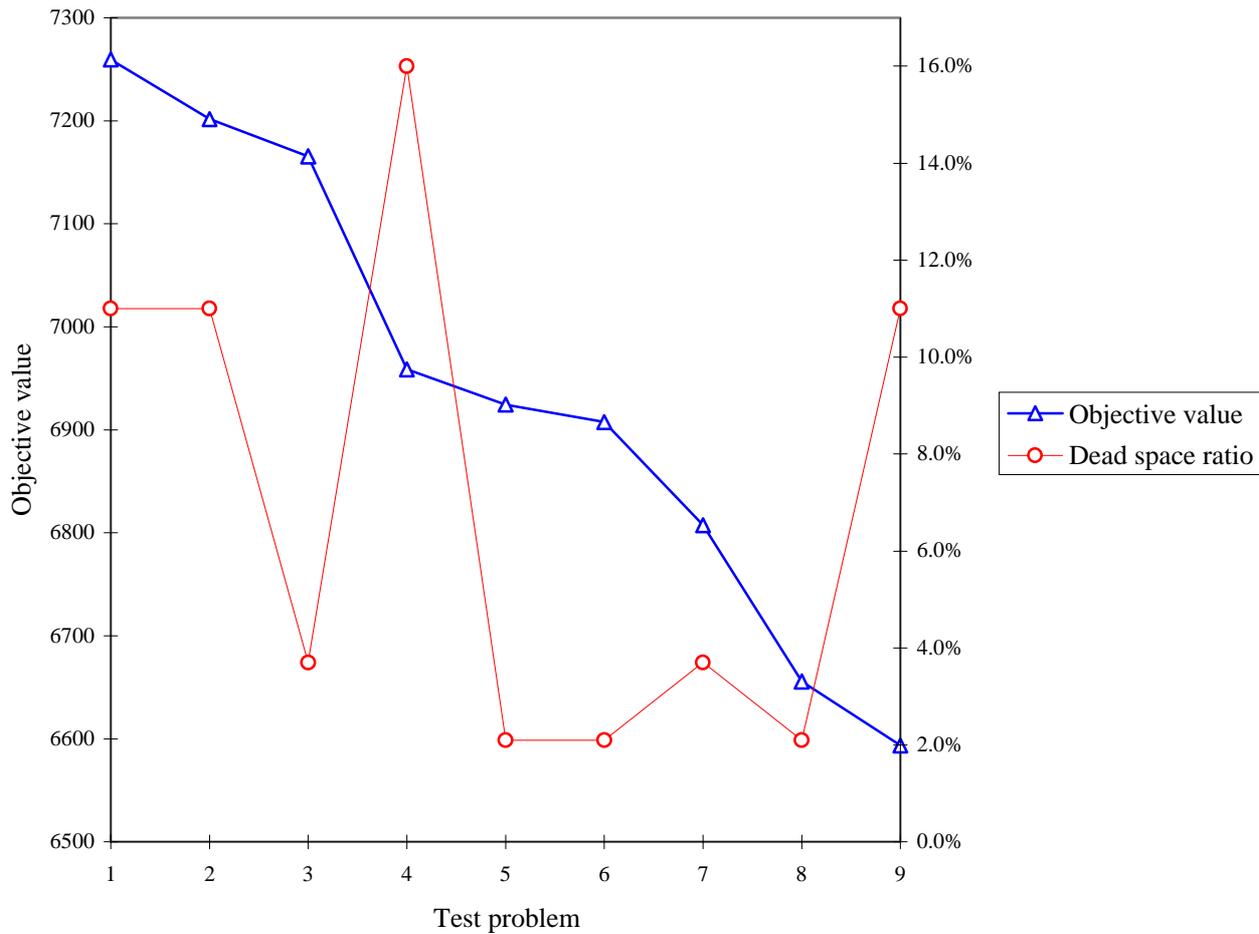


Figure 6. Nine test problems for the Wel-12, showing the objective values and DSRs.

$$\begin{aligned} \text{Total performance (\%)} &= [(\text{Total performance of the objective function value} \times \alpha) + (\text{Total performance of the dead space ratio} \times \beta)] \times 100 \\ &= [1.081 (0.6) + 4.762 (0.4)] \times 100 = 255.34 \% \end{aligned}$$

5. CONCLUSION

This paper has presented the layout solutions generated by LADEGA for unequal-sized machine layout problems considering pick-up and drop-off (P/D) points. These problems are applicable to cellular manufacturing systems. The P/D points have fixed positions along the

boundaries of machines. It should be noted that these points could be any corners of a machine. A new reference coordinate of the floor plan has been introduced to handle such problems. Two test problems (real case studies) were taken from the literature to solve 6 and 12- machines cases (Wel-6 and Wel-12).

The dimensions of some machines were taken as large as 50 by 5 to demonstrate the performance of LADEGA in handling this complexity. It should be noted that small-size dimensions of facilities are easier than the above large-sized dimensions to be assigned within the floor dimensions.

For the 12-facilities problem, the chromosome

length is at least 1500 to represent all the assigned machines as well as dummy facilities. This implies that the computational time for finding very good solutions may be high, say a few hours. Despite this complexity, the layout solutions to the Wel-6 and Wel-12 cases found so far by LADEGA were superior in overall terms to the layout solutions reported in [13]. New mutation and crossover have been proposed and designed to generate feasible layout solutions.

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